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*A strong external difference family with more than two subsets*

Strong external difference families (SEDFs) were introduced by Paterson and Stinson as a more restrictive version of external difference families. SEDFs can be used to produce optimal strong algebraic manipulation detection codes. We characterize the parameters  $(v, m, k, \lambda)$  of a nontrivial SEDF that is near-complete (satisfying  $v = km + 1$ ). We construct the first known nontrivial example of a  $(v, m, k, \lambda)$  SEDF having  $m > 2$  subsets. The parameters of this example are  $(243, 11, 22, 20)$ , giving a near-complete SEDF, and its group is  $\mathbb{Z}_3^5$ . The construction uses the point-orbits of the Mathieu group  $M_{11}$  acting on the projective geometry  $\text{PG}(4, 3)$ .

This is joint work with Shuxing Li, Simon Fraser University.